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V. D. POPOV

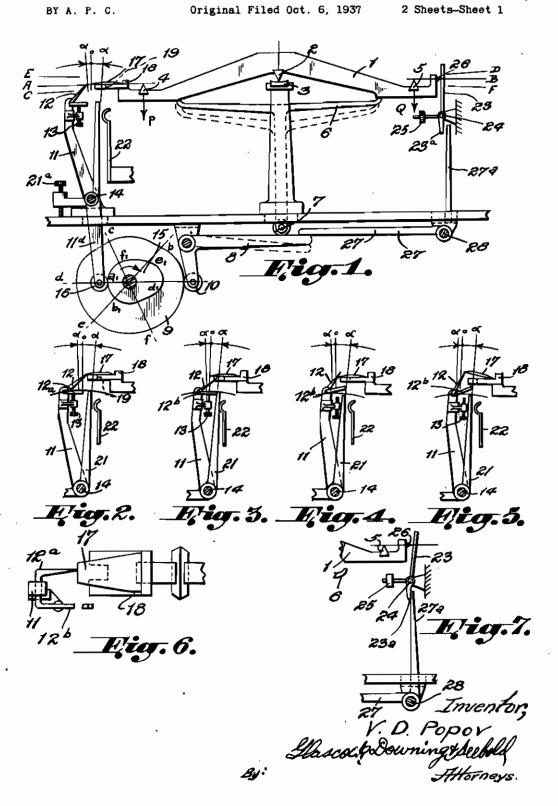
Serial No. 415,981

JUNE 8, 1943.

AUTOMATIC WEIGHING MACHINES

Original Filed Oct. 6, 1937

2 Sheets-Sheet 1



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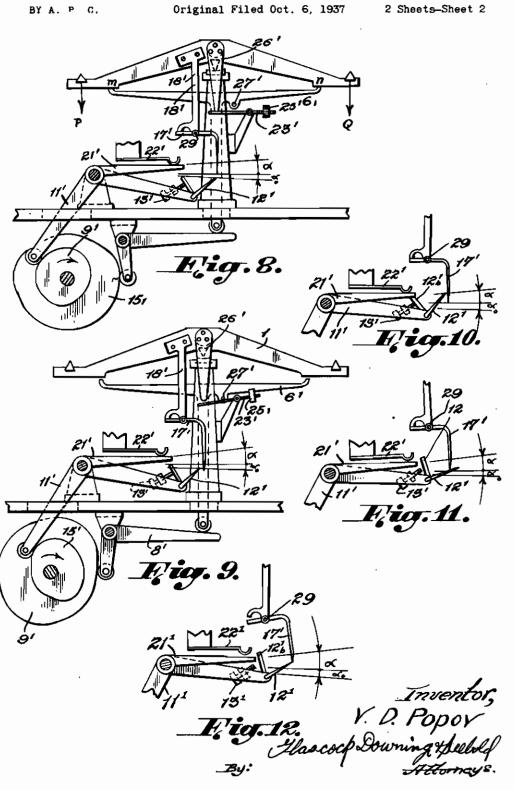
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ALIEN PROPERTY CUSTODIAN

AUTOMATIC WEIGHING MACHINES

Vladimír Dimitrijevič Popov, Prague-Bubenec, Bohemia and Moravia; vested in the Alien Propcrty Custodian

Application filed October 21, 1941

This is a division of my prior application Serial Number 167,659 filed October 6, 1937.

The scale beams adopted in automatic weighing machines hitherto known are for the purpose of determining whether the weight of a given ar- 5 ticle, or of a given quantity of a material, is greater or less than a predetermined theoretical value. in order to enable a further operation to be effected in accordance with such determination. Thus for example the scale beams in machines 10 for weighing out materials determine the weight of material upon the scale pan, and if the weight of material thereon is less than a pre-determined value, a further supply of material enters the scale pan, whereas in the event of there being a sufficient weight of material upon the pan this quantity is transferred for packing. Apparatus of this nature is disclosed U.S. Patent Number 2,198,788. In machines for sorting articles according to their weight the scale beams have the 20 same function as in these weighing out machines, that is to say, of distributing the articles in accordance with any desired theoretical limit of weight, which may be determined in grams for example, into light and heavy articles.

For the correct sorting of articles into light and heavy articles it is very important that the scale beams should be of the utmost possible sensitiveness, and that this sensitiveness should in fact be utilized in weighing. The adoption of scale 30 beams of the utmost sensitiveness, in known machines, does not however guarantee accurate working thereof, because the scale beams in automatic weighing are exposed to unfavourable conditions, which distort the normal working thereof, and prevent the weighing from being effected within the limits of sensitiveness of the scale beam. In some machines, for example, the scale beams are subjected during the weighing to the influence of individual accessory members, which, 40 during the time when material is being supplied for weighing, have a braking effect on the action thereof, the deflection of the scale beam being utilised for carrying out operations which render it necessary that the deflection should be large and powerful. Finally in some machines the scale beams move upon an endless track or the like, which in itself precludes the employment of sensitive scale beams. In these cases, however, a mechanical impulse cannot be ensured in de- 50 flections within the limits of the sensitiveness of the scale beam.

Similar circumstances preclude the possibility of weighing upon scales, particularly automatic scales, with a maximum exactitude, that is to say, 55 of the apparatus, showing various possible posi-

within the limits of very small weights, by which the sensitiveness of a scale beam is characterised. It should be mentioned that a scale beam in the position of equilibrium has no kinetic energy, and, that a very small loading of the scale beam, in the neighbourhood of the sensitiveness of the scale beam, yields a greatly retarded, small and hardly appreciable deflection, which cannot do any mechanical work, or even close the contact of an electric circuit, whereas in all automatic weighing apparatus, if the same are to work accurately, even with small deflections, in dependence upon the result of the weighing, an impulse must be given for the purpose of carrying out a 15 mechanical operation; thus for example, for the purpose of delivering or not delivering material. or for the purpose of displacing the article in the direction of the light or heavy groups and so forth.

This invention consists in apparatus for automatic weighing by the aid of a scale beam, which, however, in its work is not exposed to any influence from subsidiary members, though in dependence upon the direction of deflection of the scale beam a mechanical impulse is obtained for producing a working effect upon the article. According to the present invention any deflections, even those that are hardly perceptible, can be ascertained, and are completely sufficient, after the termination of the weighing, in dependence upon the result thereof, to give a mechanical impulse, by means of an auxiliary source of energy, for the purpose of carrying out a further mechanical operation without any cooperation of the scale beam.

The apparatus according to this invention is based upon the mutual action of a part on the scale beam, and a special feeling number, which only comes into operation after the weighing has been effected or after any deflection of the scale beam.

A further important feature of the invention consists in a supplemental arresting device which ensures correct deflection of the scale beam and proper cooperation between the scale beam and feeler.

Some embodiments of weighing apparatus according to the present invention are diagrammatically illustrated by way of example in the accompanying drawings, in which:

Figure 1 is a diagrammatic view in elevation of apparatus for carrying out the invention;

Figures 2, 3, 4 and 5 are similar views of part

tions of the scale beam after the expiration of the time allowed for weighing:

Figure 7 shows a part of the apparatus shown in Figure 1 in a different position to illustrate the release of the scale bcam, and

Figures 8 to 12 are various views showing a further modified form of construction.

Figure 1 shows ordinary weighing apparatus with a two-armed scale beam 1, which swings bearing 3. At the ends of the scale beam I there are triangular knife edgés 4 and 5, through the medium of which loads P and Q to be compared act upon the scale beam I. The scale beam I may be held at the points m and n by means of 15 any known arresting device acting in the direction of movement of the scale beam and, forming, for instance, a fork 6, which is supported by means of a roller 1 upon one arm of a lever 8, which can be deflected into the position indicated in dotted lines in Figure 1 by the co-operation of a cam disc 9 with a roller 10. The lever 8 executes such a deflection when the cam disc 9 revolves in the direction indicated by an arrow, when the point b of the cam disc comes into con- 25 tact with the roller 10. The roller 7, and with it the fork 6, then sink into the position indicated in dotted lines in Figure 1, and remain in this position during the further rotation of the cam disc 8, until the point c thereon comes into contact with the roller 10. In the lower position of the arresting fork 8 the scale beam I is completely released, and can oscillate under the influence of the loads P and Q. The time during which the part from b to c of the periphery of the cam disc 9 is passing the roller 10 is therefore devoted to the weighing. During the further rotation of the cam disc 8 through an angle corresponding to the part c to d the lever 8 rocks back into the original position and arrests the scale beam I for a period 40 during which the cam disc 9 rotates from dthrough e and f to a. Hence the scale beam, from the point d to the point a of the cam disc 9, is arrested, and during this time, by means of a known device, the load P or Q can be removed and replaced by a fresh one, or some other work can be carried out in dependence upon the purpose for which the weighing machine is employed.

The scale beam may for instance be sensitive to a loading of 0.01 gram, and from this load up- 50 Figures 3 and 4. wards is capable of deflecting from the position AB into the position CD or EF within the time during which the cam disc 9 passes with its arc b-c over the roller 10. This period is hereinafter referred to as the weighing time.

In order to determine this deflection upwards or downwards, and to give a corresponding impulse for carrying out or not carrying out a definite operation by means of an auxiliary source of energy, there is employed according to the invention an operation control means consisting for example of a member 12 bent into the shape of a hook with one sharp end and one blunt end (Fig. 6) mounted on the end of a lever II. This hook, which will hereinafter be referred to as the feeler $_{65}$ can rotate freely in the lever II in a counter clockwise direction according to the embodiment illustrated about a pivot 12a (Figure 6), while rotation thereof in a clockwise direction is prevented by an abutment or screw 13, upon which the blunt horizontal end 12b of the feeler 12 rests by its own weight. The lever 11 swings upon a pivot 14 by the aid of a cam disc (5 (Figure 1) revolving at the same time as the disc 9 about the

during which the segment a-b-c of the cam disc 9 is moving past the roller 10, a segment $a_1 - b_1 - c_1$ of the cam disc 15 moves past the roller 16, and the lever 11 is deflected through an angle α_0 so that in the position corresponding to the point c1 on the cam disc 15 the lever 11, with its feeler 12 touches a part arranged rockably on the end of the scale beam. In the example shown, the said part is formed by a blade-like upon the knife edge of a triangular knife 2 on 10 contact member 17 which bears freely upon a small table 19 secured to the end of the scale beam I and provided with a notch 19. The part 17 bears with one knife edge against the edge of the table 18, and projects with its other knife edge beyond the margin of this table. The correct position of the plate 17 upon the table 18 is ensured by its own weight.

In the event of the scale beam 1, in consequence of a difference between the loads Q and P amount to 0.01 gram or more, moving out of the position AB into the position EF when released, the aforementioned contact of the feeler 12 with the edge of the part 11 does not take place, and since the lever II, owing to the influence of the cam surface c_1-d_1 on the cam disc deflects further through an angle α , the feeler 12 passes undisturbed through the notch 19 in the table 18 underneath the part 17, as shown in Figure 3. In the event of the scale beam i, in consequence of the difference between P and Q being equal to or greater than 0.01 gram, being deflected to the left into the position CD, the feeler 12, upon the lever ii being deflected through the angle $\alpha_0 + \alpha$, engages the edge of the part 11 and is rotated in a counter clockwise direction relative to the lever 11, as shown in Figure 4. If actual contact of the point of the feeler 12 with the edge of the part 17 occurs, which is only possible when the scale beam I is at rest in its position AB, that is, for instance, when P-Q is less than 0.01 gram, the feeler 12, upon deflection of the lever 11 through the angle $\alpha_0 + \alpha$, rotates in a counter clockwise direction, and can also raise the part 17, as shown in Figure 5. The position of the feeler 12 corresponding to Figure 5 is very improbable, since during the raising of the part 17 the equilibrium at the point of contact is disturbed, and the part 17 in relation to the feeler 12, assumes one of the positions represented in

From the above description it will be gathered that the lever ii has a positive movement, and takes the feeler 12 with it towards the scale beam, so that if the part 17 were to be rigidly connected with the scale beam 1, the feeler 12, in the event of direct contact with the part 17, would have to bear against the part, and a raising of the scale beam out of its bearing 3 might occur. To prevent this, the movability of the part 17 is necessary.

It is obvious from Figure 3 that, for instance, with a load P less than Q, the feeler 12 deflects freely through the entire angle $\alpha_0 + \alpha$ without meeting the part 17 and bears with its blunt end 12b against the lever 21. This lever 21 serves as release organ, whose movement may be utilized for operating a known mechanism which carries out certain manipulations with the article on the scale, for instance, it removes said article and puts a fresh one in its place, or it carries out other manipulations which are dependent on the purpose for which the scale beam is intended. It is also possible to utilize the movement of the lever or release organ 21, for instance, through same axis, and of a roller 18. Within the time 76 the medium of a contact spring 22 for switching.

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on an electric current of any known device (not shown) which carries out the corresponding manipulations with the article. The lever or the release organ 21 normally assumes the position shown in Figure 1; this position is determined, 5 for instance, by a regulating screw 21a (Fig. 1) arranged on the left arm of the lever 21. The said regulating screw 21a prevents a deflection of the lever 21 to the left while a deflection to the right is effected by the blunt end 12b of the feeler 10 12 bearing against the said lever so that this lever is moved to the right (Fig. 3) and comes in contact with the contact spring 22 which, as stated above, is adapted to switch on an electromagnetic device. When the feeler 12 meets the part 17, 15 as shown in Fig. 4, the end of the feeler 12b moves upward whereby it does not meet the lever or release organ 21, that is to say the release organ 21 is not actuated so that the corresponding mechanism is not set in operation.

As regards the case illustrated in Figure 5, the arm 12b likewise cannot rock the lever 21 for the purpose of giving contact with the spring 22, and the article is automatically transferred to the category of heavy articles. If however the posi- 25 tion of the feeler 12 after contact with the part 17 is changed into the position illustrated in Figure 3, the article is transferred into the category of light articles. On this ground in the event of the weight of the article differing from a pre- 30 determined theoretical value by an amount smaller than that by which the sensitiveness of the scale beam is characterised, for instance 0.01 gram, or in other words if the scale beam executes no deflection, a transfer of the article into 35 the category of heavy articles is possible in the same manner as the transfer thereof into the category of light articles, because its weight lies at the theoretical boundary between the two categories. Articles of a weight which differs 40 from a pre-determined theoretical value by a magnitude characterising the sensitiveness of the scale beam, for instance by 0.01 gram, or by a greater value, are transferred to the corresponddisc 15 onwards, the lever 11, together with the feeler 12, owing to the action of the cam d_1 $e_1 - f_1 - a_1$, can execute a return movement into the original position (Figure 1), that is, within arrested, as will be seen from the cam disc 9 in Figure 1, for the purpose of effecting, during the time of its arrest, any desired operation on the article weighed, for which purpose an impulse has been given by the lever 21.

It may be observed that the part 17, as already described, is rockable on the scale beam 1, that is to say, can raise itself, as indicated in Figure 5. Such a construction of the part 17 is for the purpose, as already mentioned, of preventing 60 the knife edge 2 from being displaced relatively to or raised out of its bearing 3, at the moment of contact of the part 17 with the feeler 12. This measure is indispensable if the sensitiveness of the scale beam I is to be preserved.

The feeling means described can only work accurately under the condition that the deflection of the scale beam immediately following the moment of release of the scale beam by the stop occurs on the right side, that is, on the side 70 of the greater load, P or Q. Not one of the known arresting devices all of which act in the direction of the deflections of the scale beam can however ensure such regularity of the deflection of the scale beam, because on account of moisture, dirt 75 youd the said angle.

or other hitherto undiscovered causes the scale beam adheres to the arresting members, and is practically never released at the two points m and n at exactly the same moment. Such a phenomenon can as a rule be observed in the manually controlled balances in chemical laboratories, and for this reason the first deflection is always ignored therein, and the weight of the article is judged by observing a number of successive deflections, or is noted after the scale beam has come to rest. These circumstances have the result that after releasing the arrest, the scale beam does not remain at rest, either when there is complete equality between P and Q or when there is a slight difference between them, but can oscillate to one side or the other, so that the feeler may yield an inaccurate weighing result, and may therefore occasion an error in the action of the machine. If for instance on the left arm of the scale beam i in Figure 1 the load P is lighter than the load Q by 0.01 gram, the scale beam should adjust itself into the position EF. In consequence however of adhesion of the scale beam at the point m to the arresting fork 6, the scale beam may swing, after release, out of the position AB into the position CD. If this incorrect deflection occurs at a time when the arc b-c of the cam disc **9** is acting upon the roller 10 it is obvious that an article, which in itself is light, may be disposed of as if it were a heavy article.

The suitability of the feeler is therefore conditioned by a correct direction of the first deflection of the scale beam, which according to the present invention is attained by means of a secondary arresting device, which is illustrated in Figures 1 and 7, and which consists for example of a three-armed lever freely rotatable upon the pivot 24. The arm 23 of the three-armed lever is pressed lightly against the point of a pin 26, secured to the scale beam 1, by the influence of a weight 25 loading the three-armed lever. After release by the primary arresting device 6 the scale beam still remains under the influence of ing category. From the point d_1 on the cam 45 the three-armed lever, which, by friction of the arm 23 on the point of the pin 26, reduces the sensitiveness of the scale beam for a time, for instance for so long as the point b on the cam disc 9 is not in contact with the roller 10, so that the time in which the scale beam can already be 50 the aforementioned adhesion at the points mand n by the scale beam is not perceptible, and therefore does not bring about any deflection of the scale beam at the wrong time. As soon as the arresting fork 6 assumes its lower position, indicated in Figure 7, and in Figure 1 in dotted lines, which occurs at the point b of the cam disc 9 (Figures 1 and 13), a stoppage of the secondary arresting appliance is effected, this being by the aid of a lever 27, rotatable upon a pivot 28, and resting upon the lever arm 8. An upwardly directed arm 27a of this lever strikes against a downwardly directed arm 23a of the three-armed lever 23 and rocks the same in a ciockwise direction, as a result of which the arm 23 of this three-armed lever releases the pin 26, and therefore the scale beam I also, wherein any movement occurs with zero velocity exclusively under the influence of the loads P and Q. The moment of release of the scale beam by the secondary arresting device therefore constitutes the beginning of the weighing, that is, at the point b on the cam disc 9. The end of the weighing occurs at the moment at which the feeler 12 touches the edge of the blade 17 or travels be-

It is quite clear that with a sufficiently large difference between the loads P and Q, regardless of the adhesion of the scale beam at the points m and n, the first deflection of the scale beam will always be in the right direction, and may take place even before the stoppage of the secondary arresting device. In the case of small difference between P and Q, and the adhesion phenomena at the points m and n, the correctness of the scale beam deflection is ensured by 10 the employment of the secondary arresting device 23 described. For a scale beam of very high sensitiveness, particularly a scale beam for weighing small doses or light articles, another embodiment of the device described is provided 15 by the present invention, wherein the action of the feeler 12 upon the part 17 and the action of the secondary arresting device 23 upon a supporting member are opposite in direction to the action of gravity upon the scale beam i itself. 20

These devices, and the manner in which they co-operate, are diagrammatically illustrated in Figures 8 and 9, in which the parts serving the same purpose as those of Figures 1 and 13 are denoted by the same references, which are however distinguished by the index 1. Thus for example the part 17 of Figures 1 to 7 is denoted in Figures 8 and 9 by the reference 111. The part 171 of Figures 8 and 9, provided at its lower end with a knife edge, is rotatably sup- 30 ported upon a pivot 29 on a holder 181 secured to the scale beam 1. The duty of the pin 26 of Figures 1 and 7 is here allocated, in Figures 8 and 9, to a tongue 281, against the lower end of which a secondary arresting lever 231 bears un- 35 der the action of a weight 251, and thereby damps out undesirable deflections of the scale beam, which arise at the points m and n upon release by the primary arresting fork 61 by means of the lever 81 and the cam disc 91. The second- 40 ary arresting lever 231 sets free the scale beam ! owing to the fact that a pin 271 secured to the fork 81, when the fork 61 descends, brings the lever 231 from the lower end of the tongue 261 into the position represented in Figure 9. The 45 method of action of the feeler needle 121, which is rotatable on a lever 111 deflecting by the action of the cam disc 15^1 in an angle $\alpha_0 + \alpha$ and maintained in its position by a screw 131 for example, is completely analogous to the action of the feeler 50 position. 12 of Figures 1 to 6. In Figure 10 a position is

represented in which the scale beam, by the action of the loads P and Q, together with the part 171, is deflected in a counterclockwise direction, so that the feeler 121, upon the lever 111 being deflected through the angle $\alpha_0 + \alpha$, deflects freely in the same manner as in Figure 3, and acts by its end 12b1 upon the lever 211, which touches a contact spring 221 for example. Figure 11 shows a case in which the scale beam i is deflected in a direction opposite to that of Figure 10, so that the part 171, with its lower end, places itself in the way of the feeler 121, which changes its position in relation to the lever ill, and does not influence the lever 211 by lts end 12b1. Finally, in Figure 12, an unstable position of the feeler 121 in relation to the part 171 is represented, which may change with equal probability into either of the two positions mentioned (Figures 10 and 11), and which corresponds to the positions represented in Figure 5 of the first em-

The appllances described, therefore, are for the purpose of providing for accurate automatic weighing on a scale beam, for the purpose of sorting articles according to their weight, or adding material in relatively light doses, as in U. S. Patent No. 2,198,788.

By the co-operation of scale beam, I, a secondary arresting device 23 and a needle like feeler 12, the problem is solved of obtaining, by means of a secondary source of energy, for instance by means of an oscillating or other movement of the lever 11 together with the feeler 12, an impulse for carrying out mechanical operations which are required for the operation of automatic weighing machines. The scale beam is herein exposed to no subsidiary influences during the period of the weighing, and therefore accomplishes merely its own purpose, namely the weighing, and does no work directly by its own deflection, so that the sensitiveness of the same is fully utilised. The impulse for carrying out or not carrying out a mechanical operation is given in reallty by the indicator member, which determines, at a pre-determined moment after the weighing, the condition of the scale beam. that is to say the position of the scale beam at this instant, and gives or refrains from giving a mechanical impulse in dependence upon the said

VLADIMÍR DIMITRIJEVIČ POPOV.