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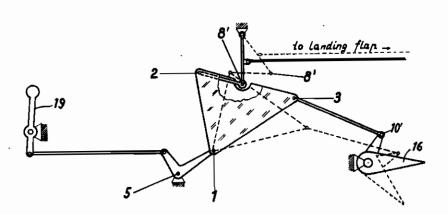
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CONTROL MECHANISM FOR AIRCRAFT

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Fig. 3



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CONTROL MECHANISM FOR AIRCRAFT

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The present invention relates to a system for operating rudders in aircraft.

Control systems for aircraft have been proposed in which the ratio of transmission between the controlling member, for example, a stick, and the member to be controlled, for example, a rudder, changes automatically in a predetermined manner during operation of the system. It is desirable to make the change of transmismember to be controlled.

For controlling or steering aeroplanes, it is desirable that, in the neighborhood of the centre or neutral position, comparatively small deviations of the member to be controlled, for ex- 15 ample, the rudder, are produced by relatively large movements of the controlling member, for example, the stick, and that in the range of larger deviations or control movements away from the centre or neutral position, the movements of the rudder or the member to be controlled are gradually accelerated, so that at first the movement of the rudder lags behind that of the stick, and when reaching an end position, the movement of the rudder leads that of the stick. There is no linear relation between the movements of the controlling member and the member to be controlled. Various means have been proposed to solve the above set forth problem. The conventional mechanisms inherently have plenty of play and the member to be controlled, for example, the rudder, tends to flutter at certain operating conditions. Coulisse guides and similar means have been proposed; such means are subject to wear and are inferior to the mechanism according to the present invention which is composed of levers.

According to the present invention, the problem is solved by the provision of mechanical movement transmitting means, including a lever mechanism, made of novel construction, which is interposed between the controlling or manipulated member and the member to be controlled.

the present invention will be apparent from the accompanying specification and claims and shown in the drawings which, by way of illustration, show what I now consider to be preferred embodiments of my invention.

In the drawings:

Figure 1 is an isometric diagrammatic showing of the mechanism, according to the present invention.

Figure 2 is a diagrammatic top view of a modi- 55 or centre position. In the arrangement shown

fied mechanism, according to the present invention.

Referring more particularly to Figure 1 of the drawings, it will be observed that the mechanism, according to the present invention, does not include gliding members, such as coulisses. The mechanism, according to Figure 1, may be arranged to produce a self-braking and selflocking effect, in the neighborhood of its cension ratio dependent on the deviation of the 10 tre or neutral position, so that movements of the rudder, caused, for example, by wind forces, cannot be transmitted to the stick, although movements of the stick are always effective on the rudder.

> The mechanism is preferably mounted on a base plate or suitable casing 14. Three fulcrums, or pins, 5, 8 and 12, are fixed to said base plate. Levers 4, 7 and 11, respectively, of suitable length and configuration, are adapted to 20 swing about said fulcrums.

A substantially triangularly-shaped coupling element 15, carries at its corners articulation pins 1, 2 and 3. Pin 1 is connected to the end of driving lever 4, which swings about pin 5, 25 which is rigidly connected with plate 14. Driving lever 4 may be operated by means of control wires 6, which connect lever 4 with a steering wheel, a stick or the like. Pin I swings on an arc. Pin 2 is connected with the end of lever 7 and its distance from fulcrum 8 is maintained at all operating positions so that the movements of the coupling triangle 15, particularly of pin 3, are definitely determined; pin 3, as every other point of triangle 15, moves along so-called coupling curves. To pin 3 one end of pusher rod 9 is movably connected. The other end of pusher rod 9 is articulated to pin 10 at the end of driven lever []. Pin 10 moves on an arc about fulcrum 12. Control wires 13 or the like are connected with lever [] and transmit the movements of lever II to the member to be controlled. for example, a rudder, an aileron or the like. By suitably arranging size, distance and configuration and location of the individual members of Further and other objects and advantages of 45 the transmitting mechanism, a great variety of transmission ratios and characteristics can be obtained, so that in spite of the unsymmetric, kinematic arrangement, a symmetric effect is produced as is desired for control systems with which the invention is concerned. A self-braking or self-locking effect, in the neutral position of the system, may be produced by arranging pins 1, 3 and 5, as well as pins 2, 3 and 8, in a straight line, when the system is in neutral

in Figure 1, only the first of the above set forth two conditions are fulfilled, and a self-braking effect is not produced in the system, according to Figure 1.

A self-braking effect is obtained when arranged as in Figure 2. This self-braking arrangement is shown in self-braking position, whereby the rudder or aileron 16 and the system are blocked against actions on the rudder itself. In the mechanism, as shown in figure 2, instead of 10 control wires 6, or the like, a connecting rod 6' is used, and instead of the substantially T shaped levers 4 and 11, bell crank levers 4' and 11' are used. Instead of connecting wires 13, a connecting rod 13' is employed. Fulcrum 8' of the sys- 15 tem, according to figure 2, is not in fixed position with respect to the base plate 14. The position of fulcrum 8' can be changed, for example, by manipulating the crank 17 of the threaded spindle 18. By changing the position of fulcrum 208', the characteristics of the transmission of the movements of stick 19, with respect to the movements of rudder 18, can be changed while the system is in operation. Adjustment or change of the transmission ratio is desirable, for example, 25for the operation of transverse rudders or ailerons; when the aeroplane moves at high speed, no great effect of minor movements of the control stick or wheel on the allerons is needed; whereas a self-locking effect is desirable, on the other 30 hand, when operating at low speeds. Particularly when the aeroplane floats towards the landing field, the self-locking effect is without impor-

tance, whereas it is highly desirable that small movements of the stick produce large movements of the allerons.

The fulcrum of the auxiliary bearing 8' may be connected to and automatically controlled by the landing flaps or similar auxiliaries which are operated when landing. By means of such an arrangement, the allerons may be simultaneously used as landing flaps without impairing their controllability to produce the alleron effect; when the position of the control stick 18 is maintained, fulcrum or pin 1 is in fixed position; a change of the position of pin 8' will then cause change of the position of pins 3 and 10, and thereby of the aileron 16.

The size of the mechanism as a whole is unimportant. Pin or driving shaft 5, and pin or driven shaft 12, may be located anywhere in the aircraft. On the other hand the whole mechanism may be bullt in a comparatively small box and inserted as a complete unit in an existing control mechanism and disposed, for example, in the fuselage bottom or stern, or in the shell of a wing.

While I believe the above described embodiments of my invention to be preferred embodiments, I wish it to be understood that I do not desire to be limited to the exact details of design and construction shown and described, for obvious modifications will occur to a person skilled in the art.

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